

# EMT-mailbox-template Reference Manual

Generated by Doxygen 1.8.9.1

Tue Jun 16 2015 11:46:41



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# Chapter 1

## Class Index

### 1.1 Class List

Here are the classes, structs, unions and interfaces with brief descriptions:

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## Chapter 2

# File Index

### 2.1 File List

Here is a list of all documented files with brief descriptions:

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## Chapter 3

# Class Documentation

### 3.1 Mailbox< mailboxType > Class Template Reference

RTOS mailbox as an object.

```
#include <Mailbox.h>
```

#### Public Member Functions

- `Mailbox ()`  
*Define the mailbox.*
- `void begin (uint16_t number=16)`  
*Create the mailbox.*
- `bool post (mailboxType &message, uint16_t timeout=BIOS_WAIT_FOREVER)`  
*Post a message to the mailbox.*
- `void waitFor (mailboxType &message)`  
*Wait for a message from the mailbox.*
- `uint16_t available ()`  
*Available messages to be read.*

#### 3.1.1 Detailed Description

```
template<typename mailboxType>class Mailbox< mailboxType >
```

RTOS mailbox as an object.

#### Warning

Header and code for tempalte class need to be on the same unique file. I guess it isn't a bug, but a feature :/

#### See also

<http://www.open-std.org/jtc1/sc22/wg21/docs/papers/2003/n1426.pdf>

The RTOS mailbox is encapsulated as a C++ object for easier use

#### Warning

Messages must be of type typename used in declaration

### 3.1.2 Constructor & Destructor Documentation

#### 3.1.2.1 `template<typename mailboxType > Mailbox< mailboxType >::Mailbox ( )`

Define the mailbox.

##### Warning

Specify typename between brackets in declaration

```
Mailbox<typename> myMailbox;
```

### 3.1.3 Member Function Documentation

#### 3.1.3.1 `template<typename mailboxType > uint16_t Mailbox< mailboxType >::available ( )`

Available messages to be read.

##### Returns

number of available messages on the mailbox to be read

##### Note

0 = no messages available

#### 3.1.3.2 `template<typename mailboxType > void Mailbox< mailboxType >::begin ( uint16_t number = 16 )`

Create the mailbox.

##### Parameters

<i>number</i>	number of messages of the mailbox, default = 16
---------------	-------------------------------------------------

#### 3.1.3.3 `template<typename mailboxType > bool Mailbox< mailboxType >::post ( mailboxType & message, uint16_t timeout = BIOS_WAIT_FOREVER )`

Post a message to the mailbox.

##### Parameters

<i>message</i>	message to be posted on the mailbox
<i>timeout</i>	default = BIOS_WAIT_FOREVER, BIOS_NO_WAIT

##### Returns

true if message posted, false otherwise

##### Note

When using BIOS\_NO\_WAIT, message isn't posted if mailbox full. Check returned bool for result.

##### Warning

Message must be of type typename

#### 3.1.3.4 `template<typename mailboxType > void Mailbox< mailboxType >::waitFor ( mailboxType & message )`

Wait for a message from the mailbox.

## Parameters

<i>message</i>	message read from mailbox when available
----------------	------------------------------------------

## Warning

Message must be of type typename

The documentation for this class was generated from the following file:

- [Mailbox.h](#)

## 3.2 myMessage\_t Struct Reference

myMessage type for mailbox

```
#include <rtosGlobals.h>
```

## Public Attributes

- uint32\_t [chrono](#)  
*for millis()*
- char [buffer](#) [10]  
*for origin*

### 3.2.1 Detailed Description

myMessage type for mailbox

The documentation for this struct was generated from the following file:

- [rtosGlobals.h](#)

## 3.3 Semaphore Class Reference

RTOS semaphore as object.

```
#include <Semaphore.h>
```

## Public Member Functions

- [Semaphore](#) ()  
*Define the semaphore.*
- void [begin](#) (uint8\_t count=1)  
*Create the semaphore.*
- void [post](#) ()  
*Post a semaphore.*
- uint16\_t [available](#) ()  
*Available count.*
- void [waitFor](#) ()  
*Wait for the semaphore.*

### 3.3.1 Detailed Description

RTOS semaphore as object.

The RTOS semaphore is encapsulated as a C++ object for easier use

### 3.3.2 Member Function Documentation

#### 3.3.2.1 `uint16_t Semaphore::available ( )`

Available count.

##### Returns

number of available count

#### 3.3.2.2 `void Semaphore::begin ( uint8_t count = 1 )`

Create the semaphore.

##### Parameters

<i>count</i>	usually number of ressources to synchronise, default = 1
--------------	----------------------------------------------------------

##### Note

For serial port, take 1

The documentation for this class was generated from the following files:

- [Semaphore.h](#)
- Semaphore.cpp

## Chapter 4

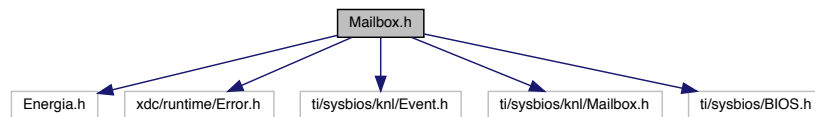
# File Documentation

### 4.1 Mailbox.h File Reference

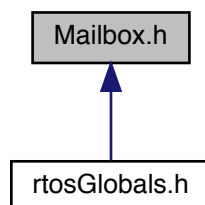
Library header.

```
#include <Energia.h>
#include <xdc/runtime/Error.h>
#include <ti/sysbios/knl/Event.h>
#include <ti/sysbios/knl/Mailbox.h>
#include <ti/sysbios/BIOS.h>
```

Include dependency graph for Mailbox.h:



This graph shows which files directly or indirectly include this file:



### Classes

- class [Mailbox](#)< mailboxType >

*RTOS mailbox as an object.*

### 4.1.1 Detailed Description

Library header.

RTOS mailbox as C++ object for Energia MT

**Project** Energia MT 0101E0016

**Author**

Energia, base  
Rei Vilo, enhancements

**Date**

Jun 14, 2015 09:53

**Version**

104

**See also**

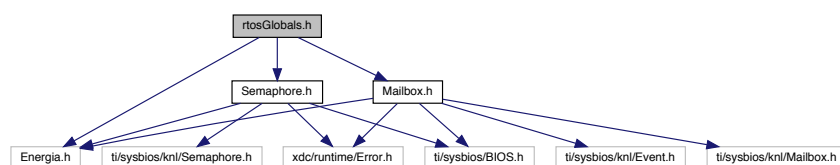
SYS/BIOS (TI-RTOS Kernel) v6.41 User's Guide (spruex3o) <http://www.ti.com/lit/pdf/spruex3>

## 4.2 rtosGlobals.h File Reference

Header.

```
#include "Energia.h"
#include "Mailbox.h"
#include "Semaphore.h"
```

Include dependency graph for rtosGlobals.h:



## Classes

- struct `myMessage_t`  
*myMessage type for mailbox*

## Macros

- #define `NUMBER` 4  
*Number of messages of the mailbox.*
- #define `MODALITY` BIOS\_WAIT\_FOREVER  
*Mailbox post modality.*

## Variables

- [Mailbox](#) < [myMessage\\_t](#) > [myMailbox](#)  
*myMailbox*
- [Semaphore](#) [mySemaphore](#)  
*mySemaphore*

### 4.2.1 Detailed Description

Header.

Global variables for Energia MT project

**Project** MultiBlink\_eX

Developed with [embedXcode+](#)

#### Author

Rei Vilo

<http://embeddedcomputing.weebly.com>

#### Date

Jun 05, 2015 13:34

#### Version

101

#### Copyright

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#### See also

[ReadMe.txt](#) for references

### 4.2.2 Macro Definition Documentation

#### 4.2.2.1 `#define MODALITY BIOS_WAIT_FOREVER`

[Mailbox](#) post modality.

#### Note

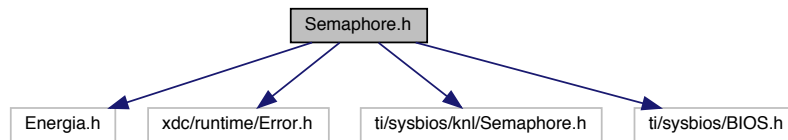
Either `BIOS_WAIT_FOREVER` or `BIOS_NO_WAIT`

## 4.3 Semaphore.h File Reference

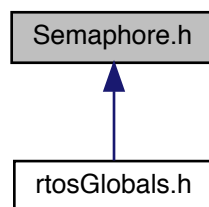
Library header.

```
#include <Energia.h>
#include <xdc/runtime/Error.h>
#include <ti/sysbios/knl/Semaphore.h>
#include <ti/sysbios/BIOS.h>
```

Include dependency graph for Semaphore.h:



This graph shows which files directly or indirectly include this file:



## Classes

- class [Semaphore](#)  
*RTOS semaphore as object.*

### 4.3.1 Detailed Description

Library header.

RTOS semaphore as C++ object for Energia MT

**Project** EMT-Semaphore

Developed with [embedXcode+](#)

**Author**

Rei Vilo  
<http://embeddedcomputing.weebly.com>

**Date**

Jun 08, 2015 09:53



### Version

104

### Copyright

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### See also

ReadMe.txt for references and example  
SYS/BIOS (TI-RTOS Kernel) v6.41 User's Guide (spruex3o) <http://www.ti.com/lit/pdf/spruex3>



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